





FORM PTO-1449 Page 1 of 2		Atty. Docket No.: H0005156 (1016.1140101)	Serial No.: 10/712,840
LIST OF PATENTS AND PUBLICATIONS FOR APPLICANT'S INFORMATION DISCLOSURE STATEMENT		Applicant: Thomas R. Ohnstein et al.	
		Filing Date:	Group Art:
		November 12, 2003	Unknown

U.S. PATENT DOCUMENTS

Examiner Initial	Document No.	Date	Name	Filing Date If Appropriate
BA	2002/0039620	04/2002	Shahinpoor et al.	
	2002/0043950	04/2002	Yim et al.	
	2002/0152006	10/2002	Bennett III et al.	
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BA	Gravagne, et al., "Kinematics for Constrained Continuum Robots Using Wavelet Decomposition, Robotics 2000, proceedings of the 4th International Conference and Exposition/Demonstration on Robotics for Challenging Situations and Environments, pp. 1-7, Feb 2000.
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22		Gravagne, et al. "Mine-Sniffing Robotic Snakes and Eels: Fantasy or Reality?," Proceedings of the 5th Intl. Symp. Technology and the Mine Problem, April 22-25, 2002 pp. 1-8.
		Gravagne, et al. "On the Kinematics of Remotely-Actuated Continuum Robots", Proceedings of the 2000 IEEE International Conference on Robotics and Automation, pp 2544-2550, April 2000.
		Hirose, et al. "Snakes and Strings: New Robotic Components for Rescue Operations," Experimental Robotics VIII, pp. 48-61, 2003.
		Horning, et al. "Polymer-Based MEMS Actuators for Biometrics," Neurotechnology for Biometric Robots, MIT Press, pp 173-185, 2002.
		Moon, B.R., et al. "Kinematics, Muscular Activity and Propulsion in Gopher Snakes," Journal of Experimental Biology, 201, pp 2669-2684, 1998.
		Paap, K.L., et al. "A Robot Snake to Inspect Broken Buildings," Proceedings of the 2000 IEEE/RSJ International Conference on Intelligent Robots and Systems, pp. 2079-2082, 2000.
22		Sofge, D., et al., "Design, Implementation, and Cooperative Coevolution of an Autonomus/Teleoperated Control System for a Serpentine Robotic Manipulator," pp. 1-7, prior to filing date November 2003.

EXAMINER: <i>Bruce R.</i>	DATE CONSIDERED: 12/2/03
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EXAMINER: Initial if citation considered whether or not citation is in conformance with MPEP 609; draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.